

# Faster Graph-Theoretic Image Processing via Small-World and Quadtree Topologies

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# Talk Outline

1. Introduction – Graphs, images and topology
2. Designing a topology
3. Small world graphs
4. Multiresolution graphs
5. Conclusion

# Graphs, Images and Topology

Zahn, C., “Graph Theoretical Methods for Detecting and Describing Gestalt Clusters”,  
IEEE Trans. on Computation, (20) 1971

Shi, J. and Malik, J. “Normalized Cuts and Image Segmentation”, IEEE PAMI, 8, (22) 2000

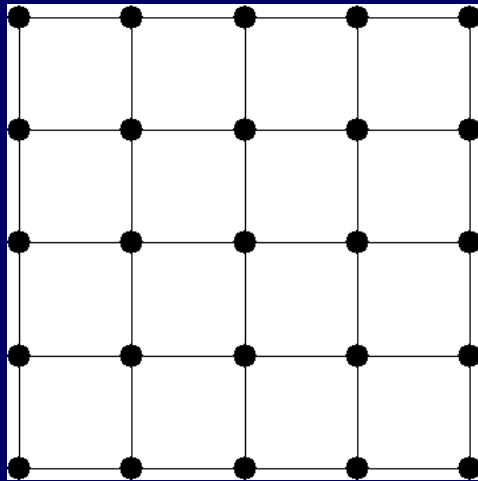
A **graph**  $G = (V, E)$  with vertices  $v \in V$ , edges  $e \in E \subseteq V \times V$ .

**Topological space:**  $\{X, \tau\}$ , where  $X$ , represents a set of elements and  $\tau$ , defines a collection of subsets of  $X$ .

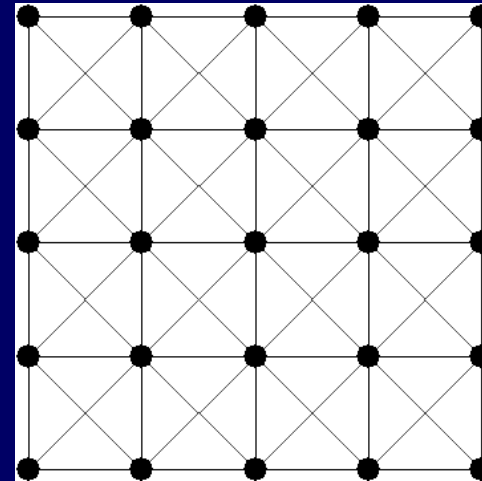
# Graphs, Images and Topology

## Standard image topologies

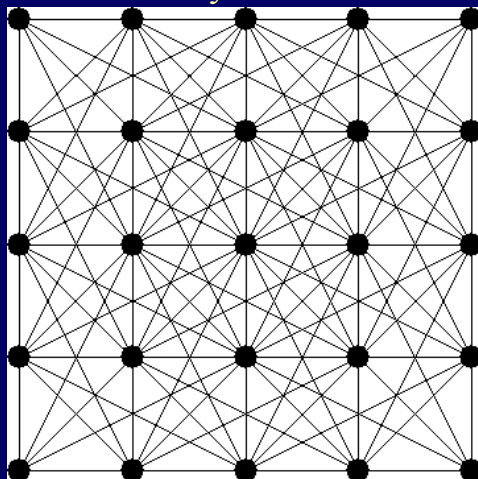
4-connected



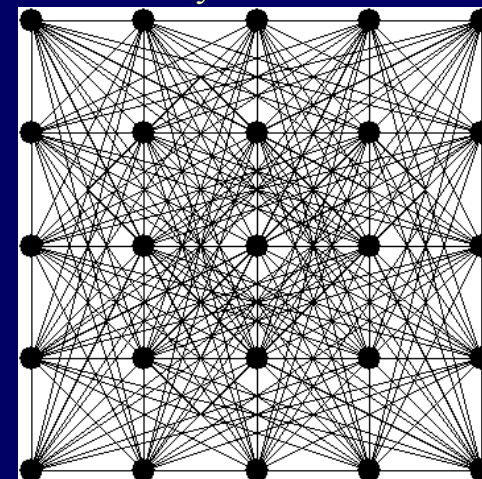
8-connected



Radially connected



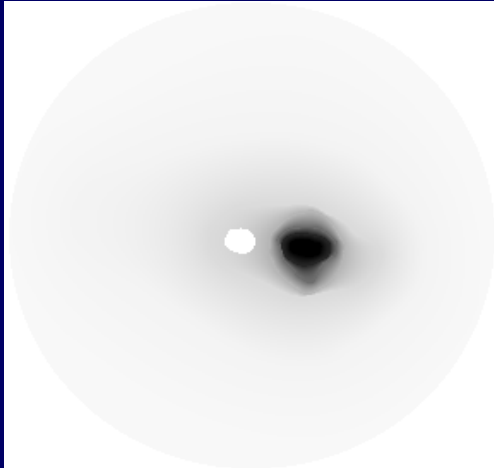
Fully connected



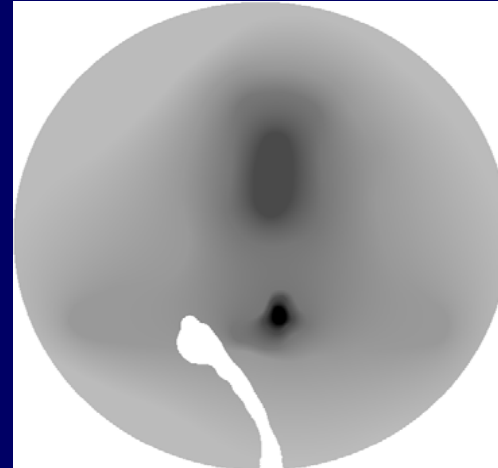
# Graphs, Images and Topology

Photoreceptor densities:

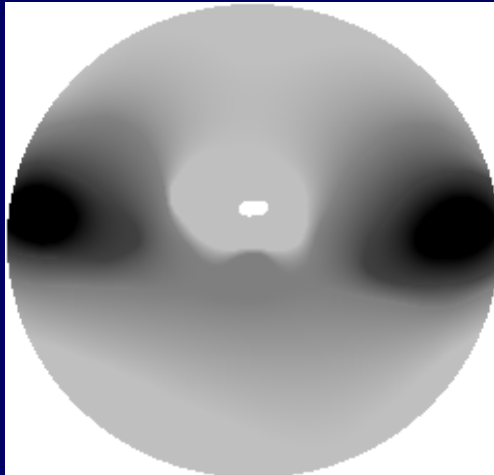
Baboon



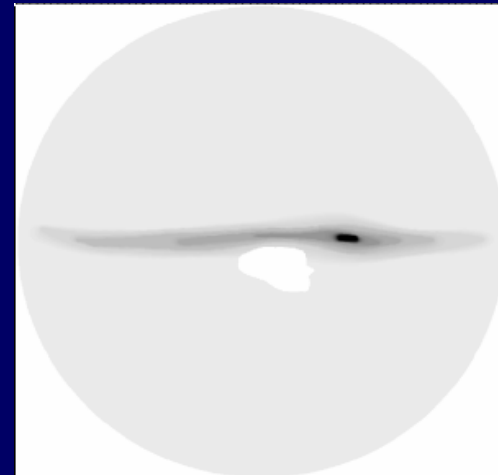
Pigeon



Dolphin



Cheetah



Evolution has driven irregular representations

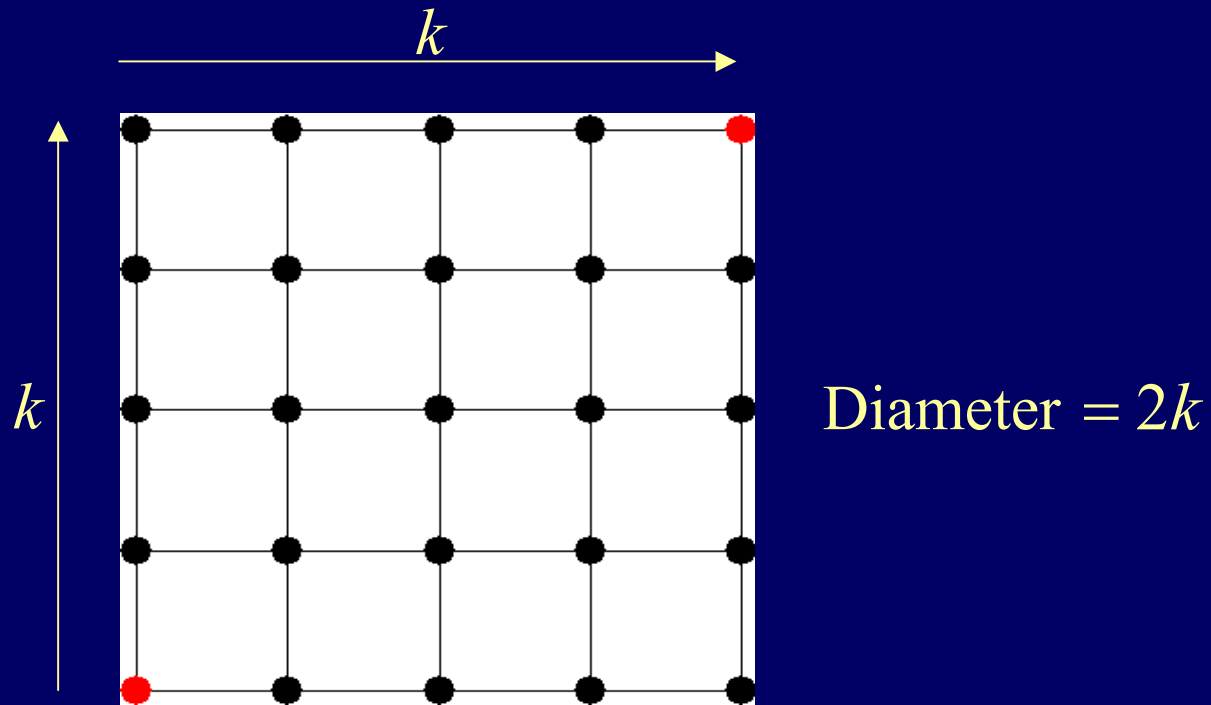
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# Designing a Topology

Principle: Choose a topology that increases algorithmic efficiency while maintaining result quality.

Graph **diameter**:

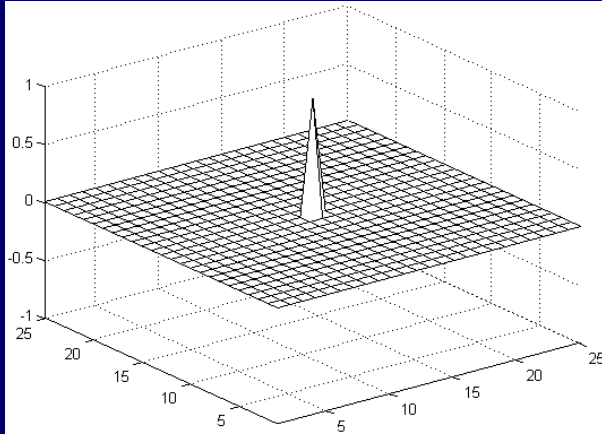


Iterative matrix methods may be thought of as a *mixing process*

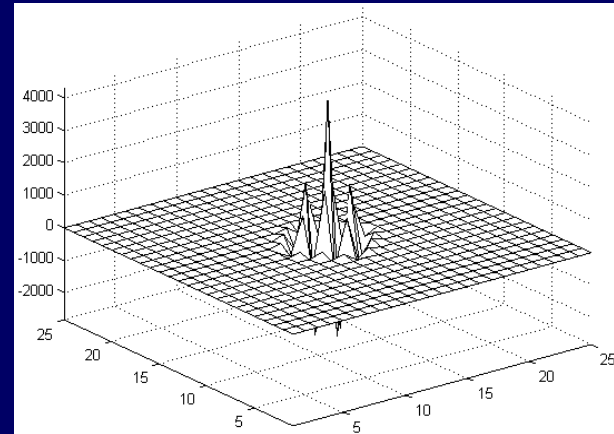
# Designing a Topology

Example: Krylov subspace bases at progressive iterations of CG with graph (finite difference) Laplacian matrix

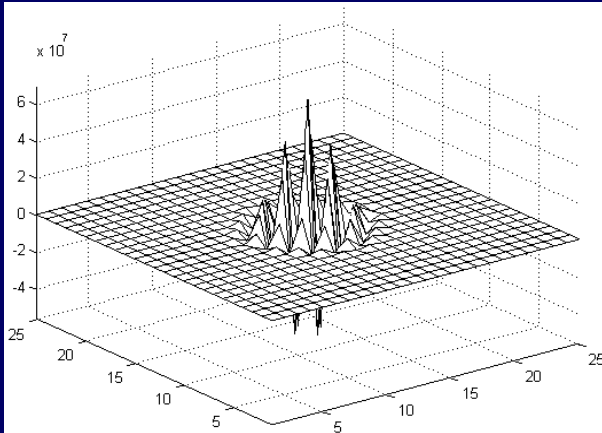
$r_0$



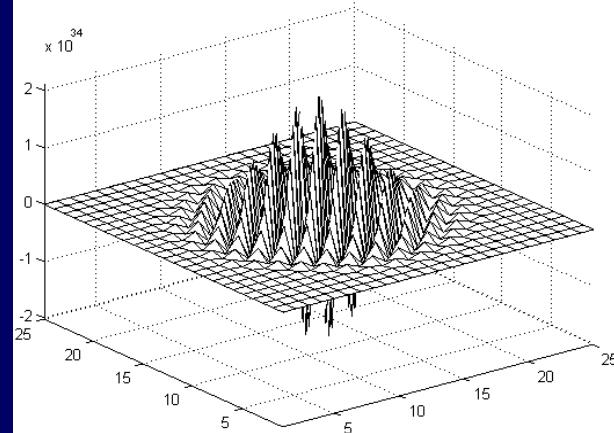
$L^5 r_0$



$L^{10} r_0$



$L^{40} r_0$



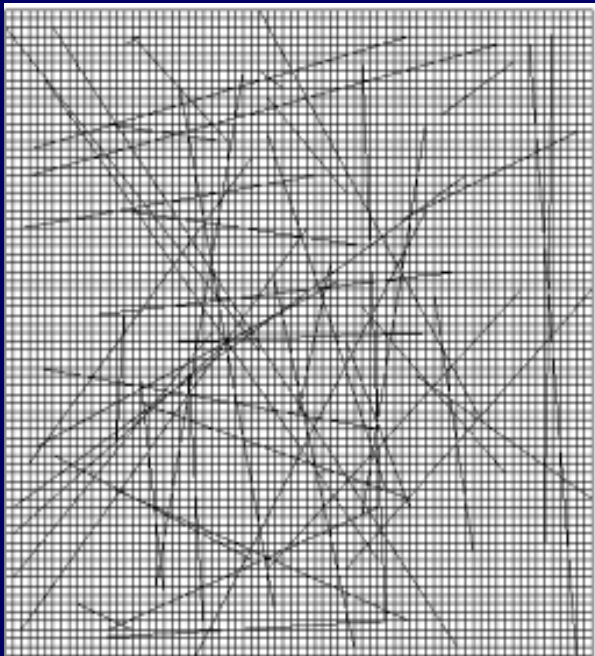


# Designing a Topology

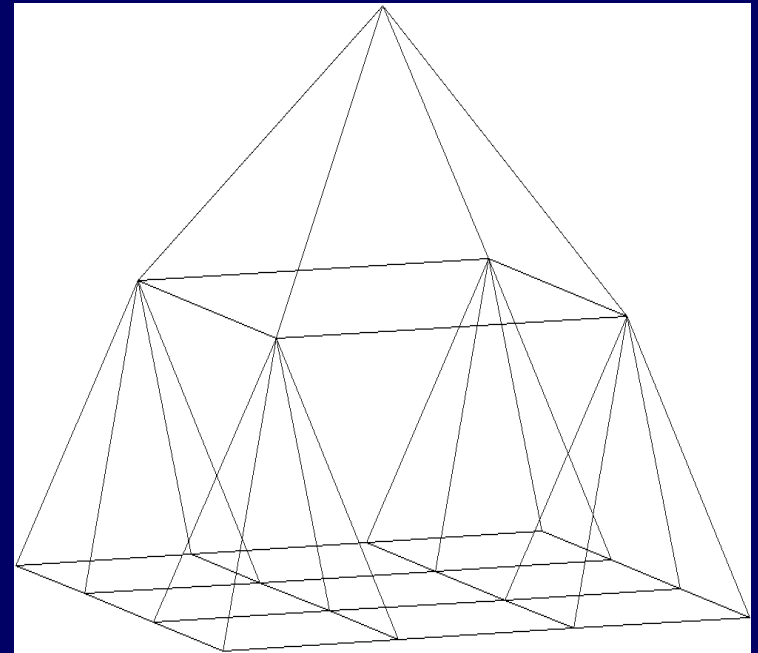
Various image processing techniques use iterative matrix methods to perform the required computations, including elliptic PDEs, diffusion, isoperimetric segmentation algorithm.

We propose two principled topologies that give small graph diameter:

Small world graph



Connected pyramid



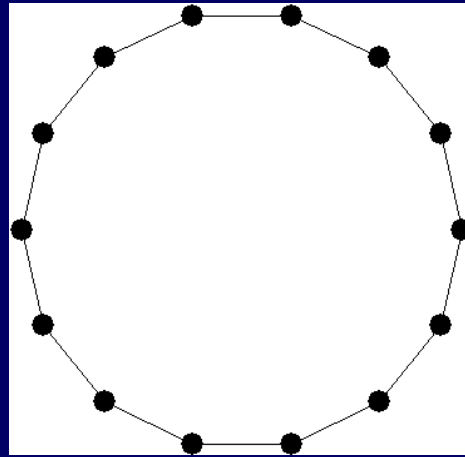
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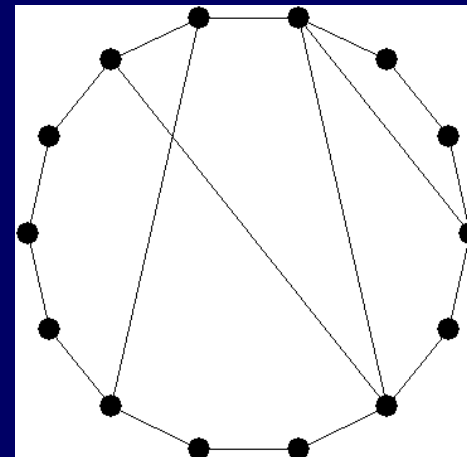
# Small world graphs

A **small-world** graph is defined as a graph that is primarily locally connected but has small diameter. A locally connected **substrate graph** may be transformed into a small world graph via the introduction of random edges.

Substrate

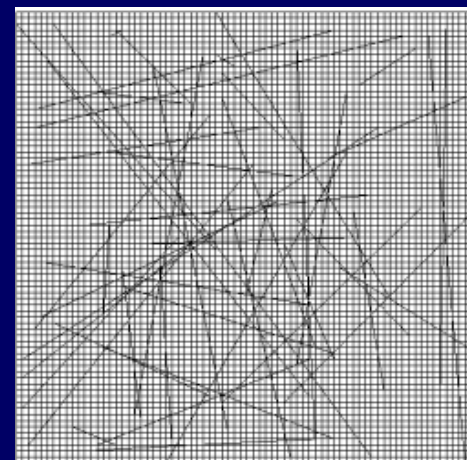
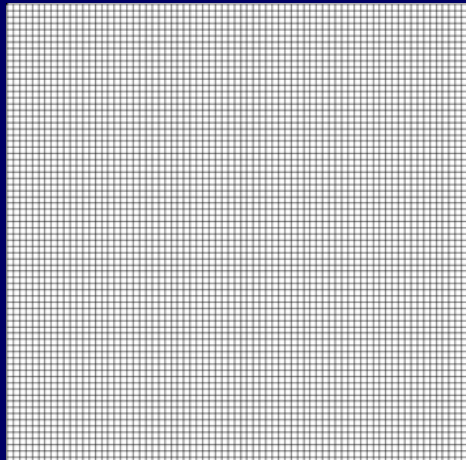


Small world



Diameter = 150

Diameter = 46



# Small world graphs

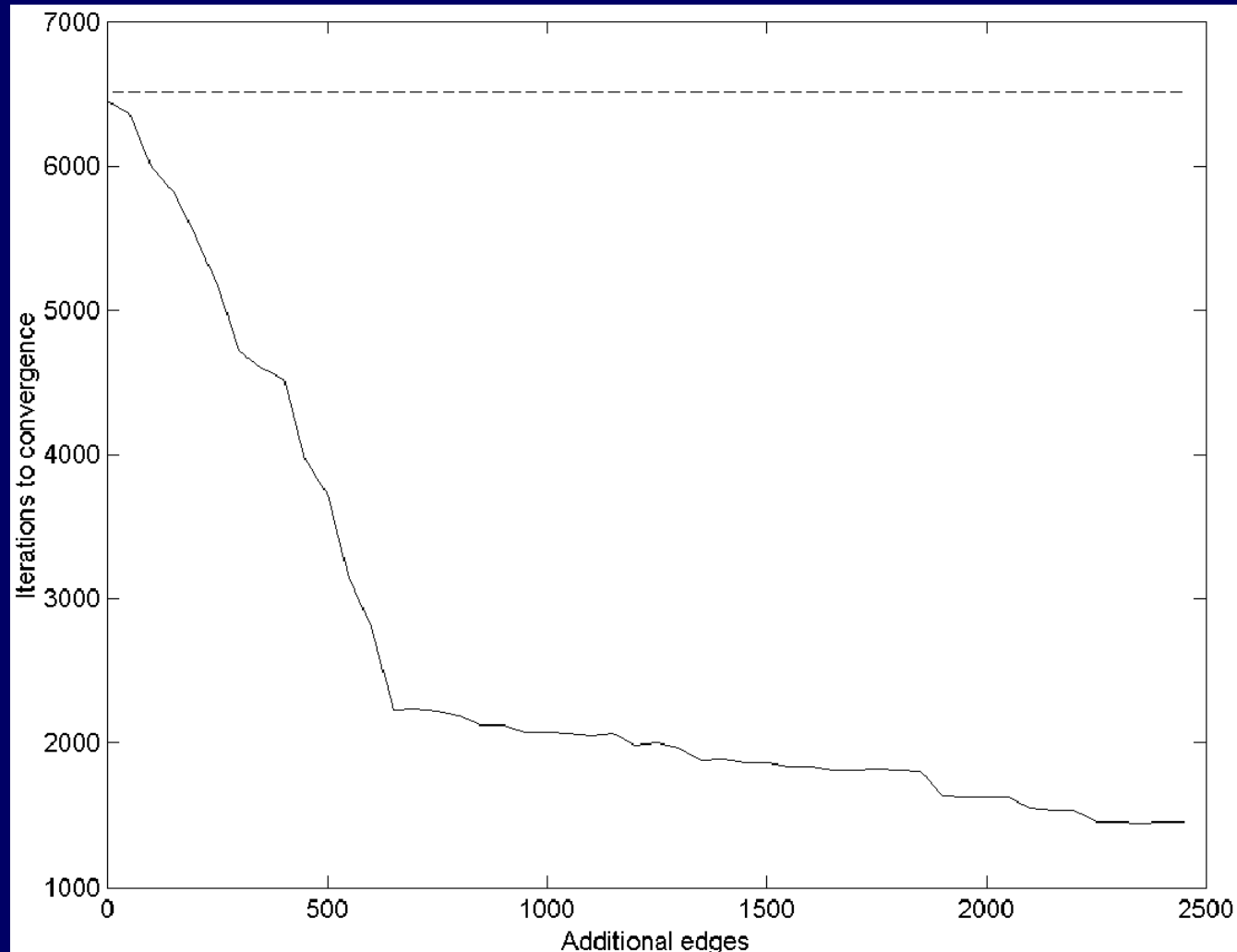
Proposal: Add a small number of random edges to a substrate graph (e.g., 4-connected lattice) in order to produce a small world graph, which retains a primarily local connectivity but has a dramatically smaller diameter.

Two issues to address:

1. At what rate does the convergence of an iterative method increase?
2. Will the results be adversely affected by the addition of random edges?

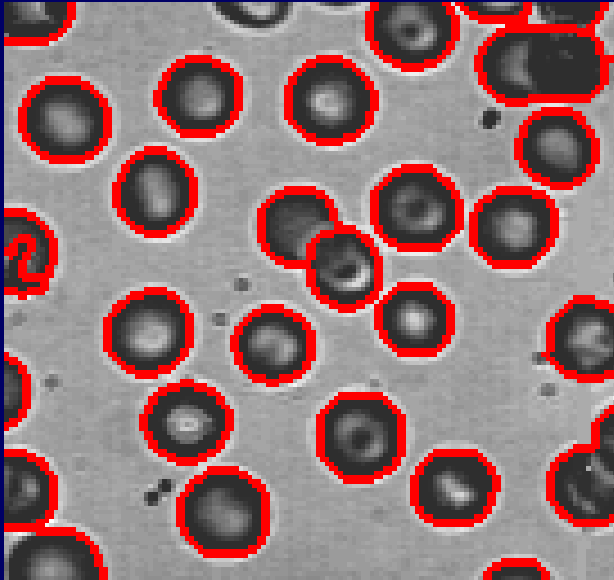
# Small world graphs

Convergence of CG as additional edges added:

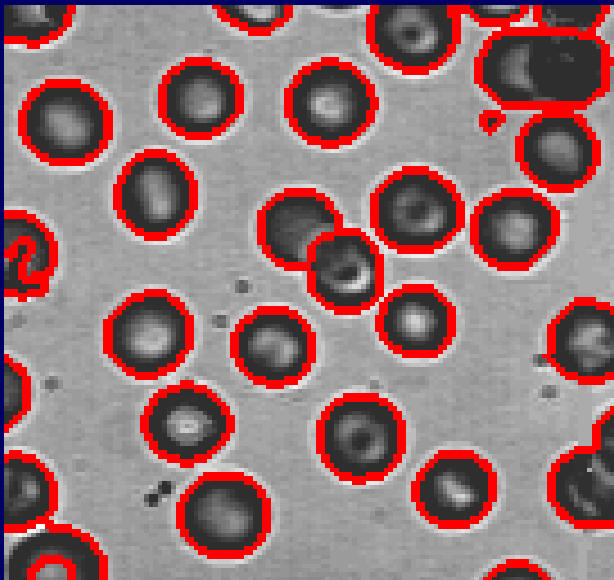


# Small world graphs

Isoperimetric segmentation

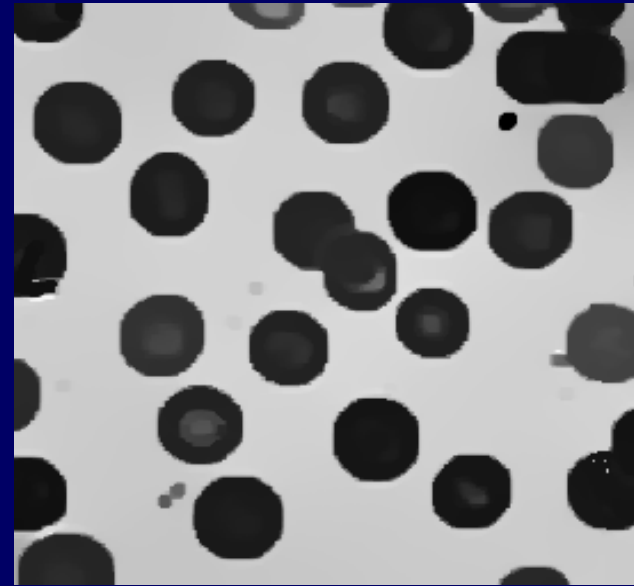


4-Connected  
Lattice

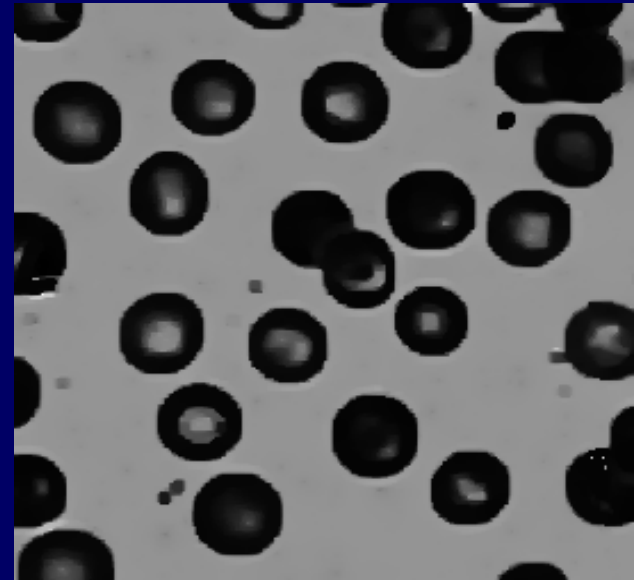


Small world

Anisotropic diffusion



Iterations  
1209



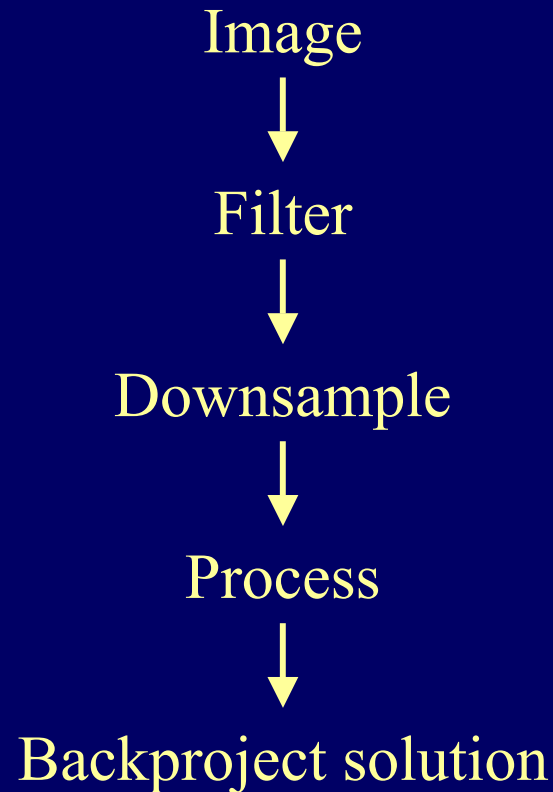
Iterations  
475

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# Multiresolution graphs

Common approach:

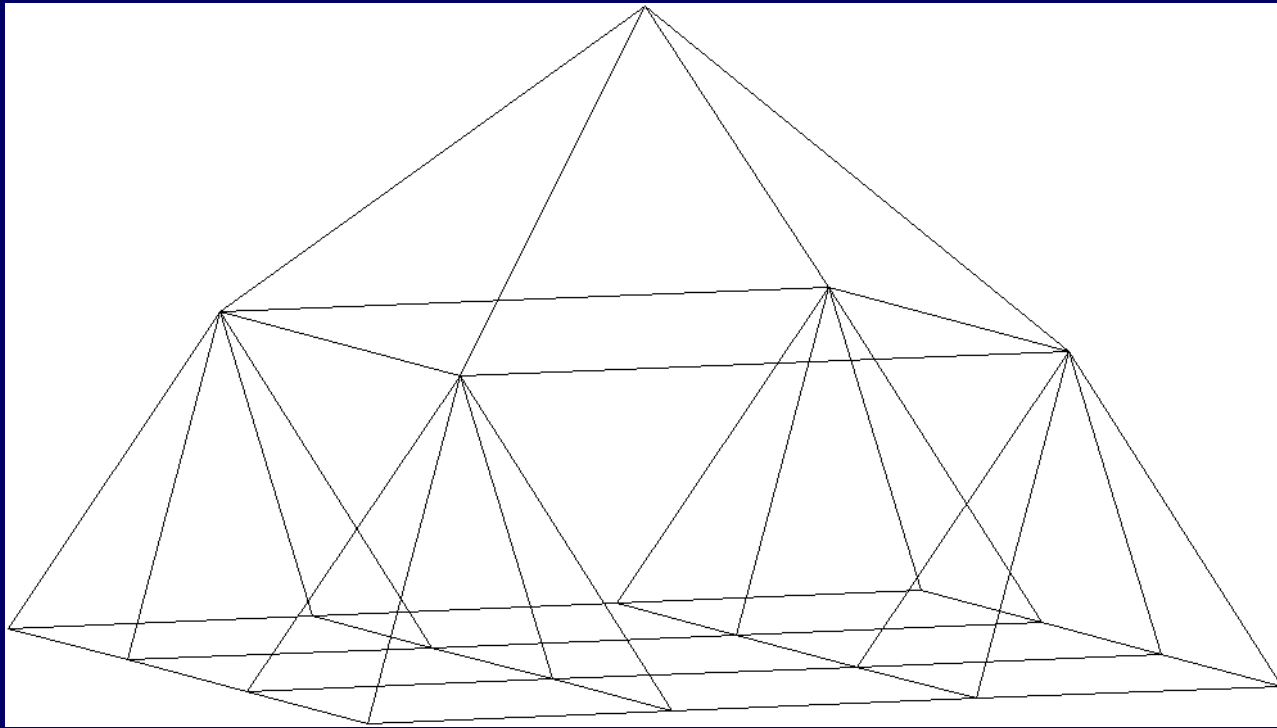


Used for speed and robustness to noise



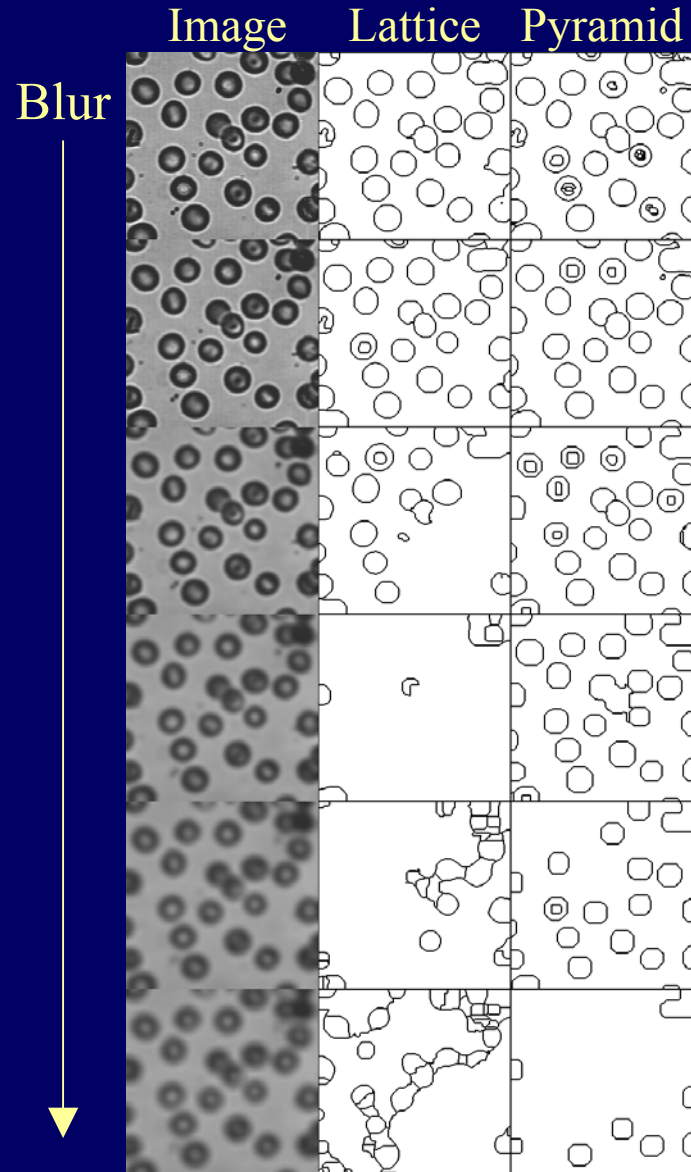
# Multiresolution graphs

Idea: Apply a graph-based analysis algorithm to the whole pyramid as a *separate graph*.



# Multiresolution graphs

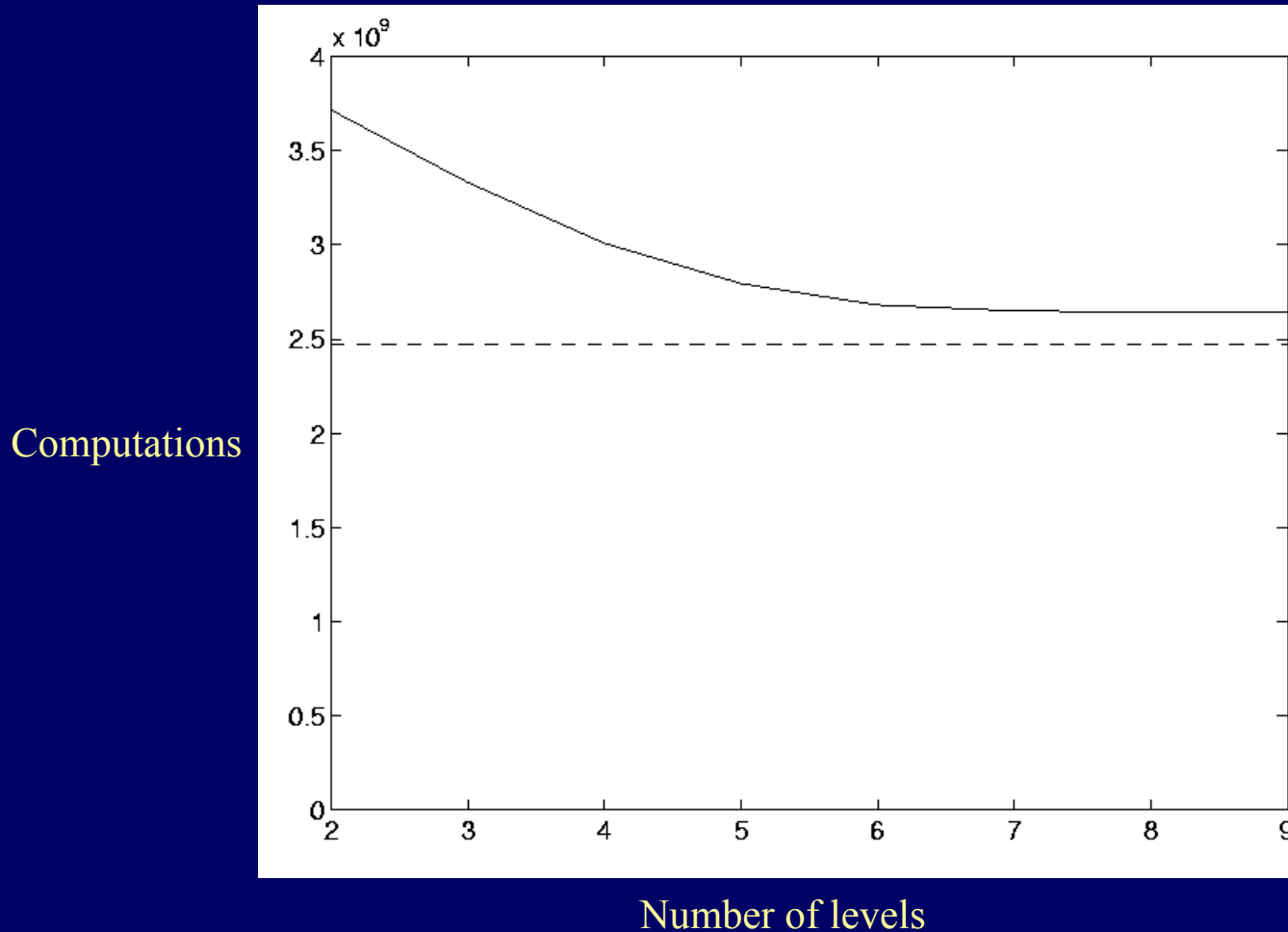
Long range connections improve performance on blurry images



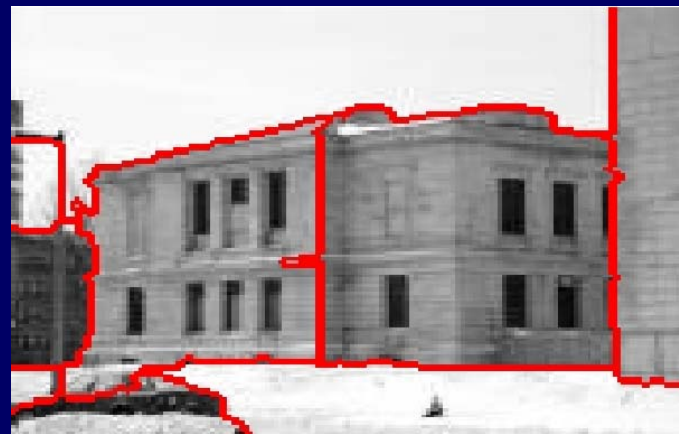
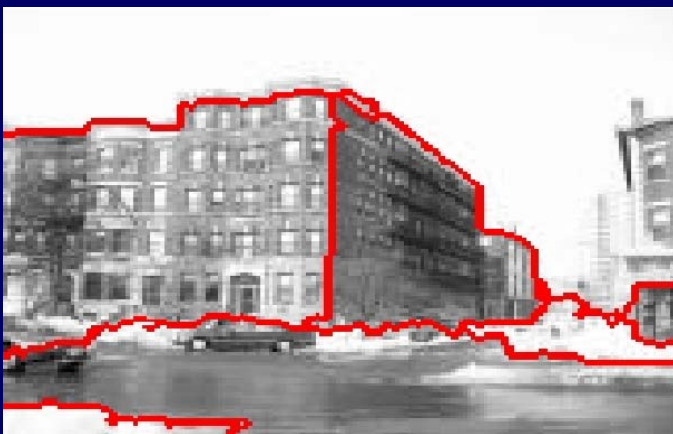
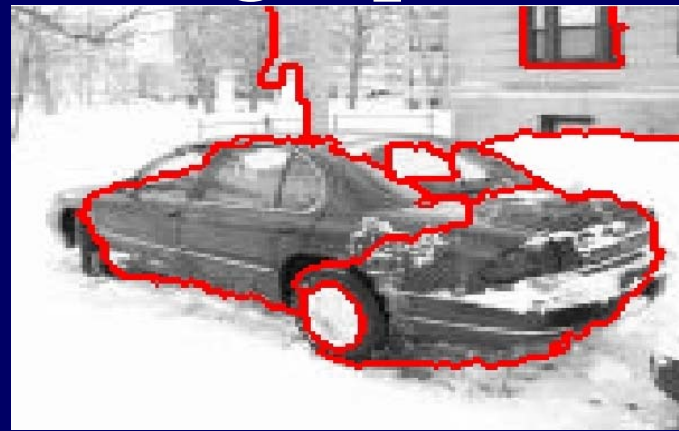
# Multiresolution graphs

Doesn't speed suffer from additional nodes?

Computations nearly the same, due to small diameter



# Multiresolution graphs



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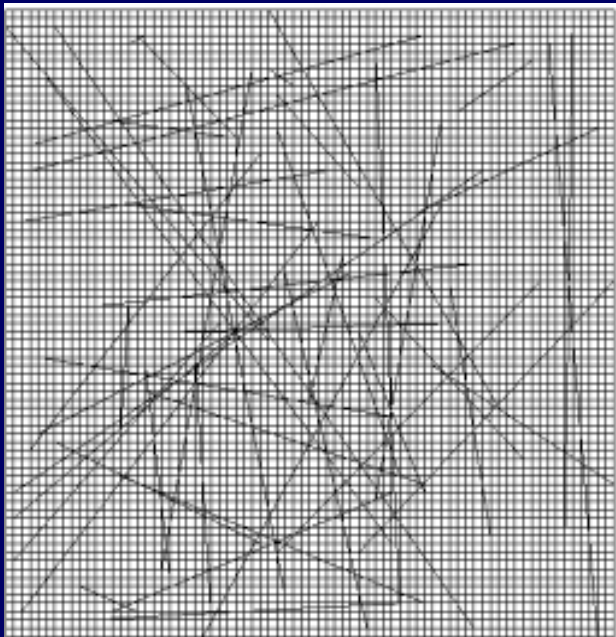
# Conclusion

We asked: Can we design an image topology that enhances algorithm performance?

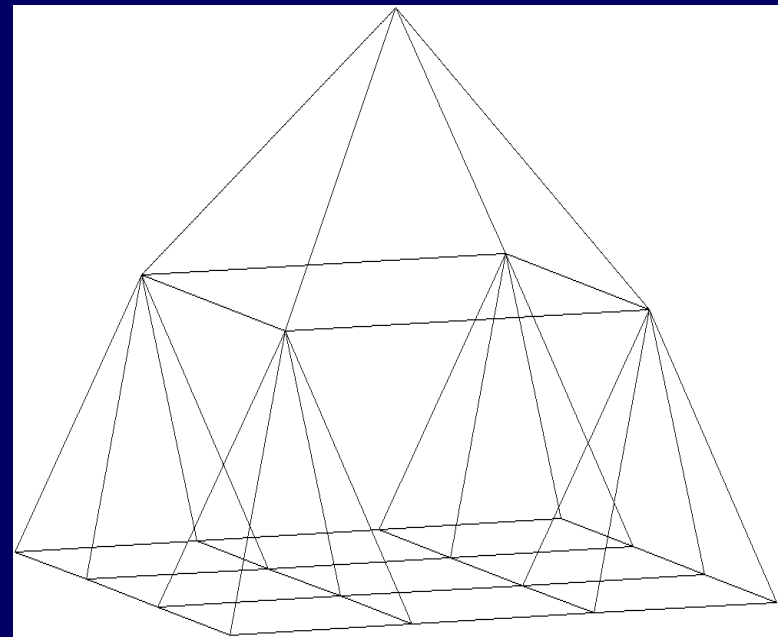
Exploit rapid convergence of mixing algorithms on graphs of low diameter.

We proposed:

Small world graph



Connected pyramid



# Conclusion

## Reproducible research

Images used in paper copyright free at:

<http://eslab.bu.edu/resources/imageDB/imageDB.php>

MATLAB toolbox for graph theoretic image processing at:

<http://eslab.bu.edu/software/graphanalysis/>

MATLAB scripts that generate each figure in paper at:

<http://eslab.bu.edu/publications/publications.php#grady2004faster>

Isoperimetric algorithm technical report:

<http://eslab.bu.edu/publications/publications.php#grady2003isoperimetric-TR>

My PhD thesis:

[http://eslab.bu.edu/publications/publications.php#grady2004space\\_phd](http://eslab.bu.edu/publications/publications.php#grady2004space_phd)

More image segmentations computed with the pyramid-based algorithm at:

<http://eslab.bu.edu/publications/grady2004faster/>

# Isoperimetric algorithm

Idea: Solve combinatorial isoperimetric problem by finding a partition that minimizes the ratio

$$h = \inf_s \frac{|\partial S|}{\text{Vol}_s}$$

Indicator function defined on the nodes relaxed to real value.

Minimization of ratio achieved by regularization through “grounding” of an arbitrary node.

$$L_M x = d$$

